**The Evolution of Vehicle Dynamics: Observational Insights from ICE to EVs**  
**Vembadi Gautham Suhaas**

Department of Mechanical Engineering, JNTUH University College of Science and Technology (UCST), Kukatpally, Hyderabad – 500085, Telangana, India.

**Abstract:**

This article presents observational insights into the evolving dynamics of vehicles, contrasting internal combustion engine (ICE) vehicles with the emerging landscape of electric vehicles (EVs). Drawing from empirical observations, the study examines key dynamic characteristics, including weight distribution, acceleration, braking performance, and noise, vibration, and harshness (NVH) levels, across diverse vehicle categories and driving terrains. The analysis further explores the impact of aerodynamics and the fundamental shift in powertrain architecture on vehicle dynamics. Specifically, the inherent weight distribution of EVs, often skewed towards the lower chassis, significantly influences handling and stability. The rapid torque delivery of electric motors yields distinct acceleration profiles compared to ICE vehicles, while regenerative braking systems alter conventional braking dynamics. Moreover, the study investigates the reduced NVH levels in EVs and their implications for driver comfort and perceived performance. By synthesizing these observations, this article aims to provide a comprehensive understanding of the transformative changes in vehicle dynamics as the automotive industry transitions from ICE to EVs.

**1. Introduction**

The rapid growth of electric cars (EVs) is causing a dramatic upheaval in the automotive industry. 1 This change is radically changing the fundamentals of vehicle dynamics, going beyond simply changing propulsion techniques. 2. The shift from the pulsating scream of internal combustion engines (ICE) to the quiet hum of electric motors requires a thorough rethinking of long-held beliefs. In order to shed light on the unique features that set EVs apart from their ICE forebears, this essay explores the complex evolution of vehicle dynamics using observational findings. We will examine how driving terrain, vehicle category, and aerodynamic concerns interact with subtle variations in weight distribution, acceleration, braking performance, noise, vibration, and harshness (NVH) levels, and more. In order to create vehicles that are both sustainable and thrilling to drive, engineers, designers, and enthusiasts must all have a thorough knowledge of these dynamic adjustments as EVs become more and more prevalent in the market. We hope to offer a thorough grasp of the dynamic landscape's progress through in-depth study, highlighting the special opportunities and difficulties brought about by the electric revolution. For engineers, designers, and fans alike, this investigation is essential as we traverse the fascinating but challenging shift towards an electric mobility-dominated future.

**2. Methodology**

* This study is based on direct observations of various ICE and EV models across multiple driving conditions. The comparative analysis focuses on key vehicle categories, including sedans, SUVs and compact cars, driven in city, highway, and hilly terrains. The study parameters include:
* **Acceleration and throttle response**
* **Braking performance** (including regenerative braking in EVs)
* **Weight distribution and handling**
* **Noise, vibration, and harshness (NVH) levels**
* **Terrain adaptability**

**3. Key Observations and Comparative Analysis**

**3.1 Acceleration and Throttle Response**

The acceleration characteristics of ICE and EVs are among their most notable distinctions. Because EVs produce torque instantly, they can accelerate from a stop more quickly. Because of this, EVs are quite responsive in stop-and-go traffic in cities. ICE cars, on the other hand, show a slow power building, with engine RPM and gearbox changes affecting acceleration. Additionally, the ICE performs better than the EVs and has higher top speeds at the higher end of the revv band.

|  |  |  |  |
| --- | --- | --- | --- |
| **Parameter** | **ICE Vehicles** | **EVs** | **Observations** |
| **Throttle Response** | Delayed due to engine rev buildup | Instant due to direct torque delivery | EVs feel more responsive |
| **0-100 km/h Acceleration** | Typically slower than EVs | Faster due to instant torque | EVs outperform ICE in sprint times |
| **Top speed** | Higher than EVs | Lower due to lack of multiple gear ratios | Multiple gears helps the vehicle to maintain high speeds with low motor RPM |

**3.2 Braking Performance**

ICE and EV braking systems are very different. While EVs use regenerative braking, which transforms kinetic energy into electrical energy to increase efficiency, decrease brake wear, and shorten stopping distance, ICE vehicles only use hydraulic braking.

|  |  |  |  |
| --- | --- | --- | --- |
| **Parameter** | **ICE Vehicles** | **EVs** | **Observations** |
| **Braking Type** | Hydraulic braking only | Regenerative + hydraulic braking | EVs recover energy while braking |
| **Brake Wear** | Higher due to sole reliance on friction | Lower due to regenerative braking | EVs require less frequent brake maintenance |
| **Braking Distance** | Varies with engine braking and ABS | Shorter due to energy recapture | EVs offer smoother deceleration |

**3.3 Weight Distribution and Handling**

EVs have **better weight distribution** due to battery placement in the chassis, leading to a **low center of gravity**. This enhances stability and reduces body roll during cornering. ICE vehicles, with front-heavy engines, tend to understeer more often, especially at high speeds.

|  |  |  |  |
| --- | --- | --- | --- |
| Parameter | ICE Vehicles | EVs | Observations |
| **Weight Distribution** | Front-heavy due to engine placement | Evenly distributed due to battery placement | EVs exhibit better balance |
| **Center of Gravity** | Higher due to engine block | Lower due to battery pack | EVs have superior stability |
| **Handling & Cornering** | More prone to understeer | More neutral or slight oversteer | EVs provide better cornering dynamics |

**3.4 NVH Levels (Noise, Vibration, and Harshness)**

EVs offer a much **quieter driving experience** due to the absence of an internal combustion engine. Noise and vibrations are significantly lower, making EVs preferable for urban commuting.

|  |  |  |  |
| --- | --- | --- | --- |
| Parameter | ICE Vehicles | EVs | Observations |
| **Engine Noise** | High due to mechanical components | Minimal, only motor hum | EVs provide a quieter cabin |
| **Vibrations** | Noticeable, especially at higher RPMs | Almost none | EVs have a smoother ride |
| **Harshness** | More road noise enters the cabin | Less due to battery insulation | EVs feel more refined |

**3.5 Driving Terrain Adaptability**

• **City Driving:** Because of their low NVH levels, regenerative braking, and quick torque, EVs perform better than ICE cars.

• **Highway Driving:** ICE cars are superior because of their longer range and faster refueling times. EVs might need to be charged more than once.  
• **Hilly Terrain:** Because EVs generate torque instantly, they may handle inclines better; nevertheless, in steep terrain, battery performance may deteriorate more quickly. Although they adapt effectively, ICE cars with variable gearbox control need more frequent gear changes.

**4. Discussion**

According to the data, EVs are perfect for spirited driving because of their superior acceleration, braking economy, weight distribution, and handling. ICE vehicles are still preferred for long-distance driving, despite issues like range restrictions and longer refueling periods. Future developments in battery technology and infrastructure for charging could close this gap even more, solidifying EVs as the preferred option.

**5. Conclusion**

This investigation of how vehicle dynamics have changed from Internal Combustion Engine (ICE) vehicles to Electric Vehicles (EVs) demonstrates a significant shift that is fueled by the basic variations in engine and design. A change in important dynamic characteristics that affect handling, ride quality, and the overall driving experience is highlighted by observational insights.

Weight distribution and improved stability and cornering capabilities are closely correlated with EVs' much lower centers of gravity as a result of battery installation. When combined with electric motors' immediate torque delivery, this significantly enhances acceleration performance and redefines responsiveness.

Regenerative braking transforms braking performance by providing precise control and enhanced efficiency. For best feel and performance, the special interplay between regenerative and friction braking calls for precise calibration. The extra vehicle mass affects ride and handling, frequently requiring strong suspension systems to preserve control and comfort. EVs' silent operation significantly lowers NVH levels, exposing previously hidden noise sources and necessitating improved vibration dampening and insulation techniques.

In order to maximise range, aerodynamics becomes more and more important, influencing design decisions to reduce drag. Additionally, the vehicle's construction can be more flexible because to the absence of an engine and gearbox, which affects both the exterior and interior design.   
EVs are more sensitive to driving terrain, especially when it comes to range and energy usage. Battery depletion is greatly impacted by aggressive driving habits and uphill gradients, necessitating the use of clever energy management devices.

Essentially, switching to electric vehicles (EVs) involves a fundamental recalibration of vehicle dynamics rather than just a change in propulsion. Although EVs have many performance and efficiency benefits, they also pose special problems that call for creative engineering solutions. We may anticipate more advancements in vehicle dynamics as technology develops, pushing the limits of what is feasible in terms of handling, ride quality, and general driving enjoyment. This development aims to redefine the fundamentals of automobile performance in a sustainable future, not only replace the engine.

**6. References**

* Rajamani, R. (2011). "Vehicle Dynamics and Control." Springer Science & Business Media.
* Wong, J. Y. (2008). "Theory of Ground Vehicles." John Wiley & Sons.
* He, H., Wang, J., & Zhang, Y. (2018). "Comparison of regenerative braking strategies for EVs." IEEE Transactions on Vehicular Technology.
* SAE International. (2020). "Electric and Hybrid Vehicle Dynamics." Society of Automotive Engineers.