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A REVIEW OF NEURAL NETWORK COMPRESSION AND PRUNING USING SHAPLEY PRUNING

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ABSTRACT

Neural network compression and pruning are two of the most vital methodologies that would make these deep architectures efficient so they can be deployed on these low-resource devices without significant deterioration in the chances of accuracy. Deep learning models are increasingly dominating NLP, computer vision, and healthcare applications and thus have witnessed an exponential increase in the related computational demands on memory for this model. This reduces the model sizes because either the precision of weight is downgraded or complexity in architecture is streamlined. In contrast, pruning results in the removal of excess weights, neurons, or even layer targeting the less impactful components a neural network. These optimizations resulted in better inference speed as well as lesser energy consumption which are crucial for this deployment in mobile platforms, Internet of things devices, and edge-computing systems. However, one of the challenges of this model simplification is the balance between efficiency and performance. Aggressive pruning and compression yield accuracy loss. Recent work on hardware-aware pruning, dynamic sparsity, and automated architecture design via NAS attempts to solve these challenges to produce more adaptive and highperformance models. Advancements in neural network compression and pruning are eyed to increase the scalability and sustainability of artificial intelligence technologies. These developments are expected to increase penetration across industries while helping the sector meet a growing need for energy efficiency in AI solutions.

Keywords- Sharpness-aware Optimization, Loss Landscape Analysis, Sensitivity-aware Pruning,Gradual Pruning, Critical Threshold Pruning

1. INTRODUCTION

The success of deep learning has driven advances in recent years in progressively more complex and powerful architectures of neural networks. These advances have promoted development in areas as diverse as image recognition, natural language processing, intelligent autonomous vehicles, and healthcare advances. However, with growing dimensions and complexity comes the corresponding need for large-scale computational resources, memory, and energy. This means that the requirement for resources would be something challenging in deploying the AI models to real-world applications, specially resource-constraint platforms like mobile devices, edge computing nodes, and even IoT devices.

Emerging techniques have been neural network compression and pruning as an effective way to overcome these challenges. This involves the reduction of model size and computational requirements by simplifying architecture or by reducing precision in weights and activations. Techniques included compression, quantization, knowledge distillation, and low-rank factorization. Pruning aims to eliminate all the less important or unnecessary neurons, weights, or even layers within a model so that only the most essential parts of the network are kept. Collectively, these techniques help to obtain faster inference times, reduce memory usage, and decrease power consumption while keeping the model's accuracy at a relatively high level.

These techniques come with a couple of trade-offs associated with them. As such, very aggressive optimization may lead to a loss in performance and accuracy; however, as the research is continually advanced, increasingly developed sophisticated methods are devised to reach an optimal balance. And these methods include adaptive pruning techniques which facilitate dynamic model pruning, hardware-aware optimizations utilizing specific computational architectures, and automated model design approaches-specifically named NAS-which seek to create highly efficient, task-specific models from the bottom-up. In this direction, neural network pruning and compression processes are not only enriching the functionalities of artificial intelligence but at the same time are bringing solutions that are energy efficient, scalable, and feasible for wide applications across all sectors. As these methodologies advance, they will increasingly be used in the conception of sustainable AI technologies, spur innovation and accessibility within the realm of artificial intelligence.

2. LITERATURE REVIEW

Shapley Pruning within Neural Networks (Derived from Shapley's Theoretical Framework)

This is based on a fundamental concept of Shapley values put forward by Lloyd Shapley in 1953. His work was motivated from cooperative game theory that looks into just distribution according to total value produced by a cooperative game among players, considering their individual contributions.

Shapley Values: A Idea in Cooperative Game Theory

Cooperative game theory is that area where players—such as neurons in a neural network—are collocating to achieve a common goal. Shapley value is a method of fairly dividing the total reward, or in this study, the performance of the model between the players based on their contributions toward the success of the group.

Shapley Value Calculation

The Shapley value assigned to a player (neuron) is determined by evaluating each possible sequence wherein players could enter the coalition, or network. For every sequence, the marginal contribution of the player (neuron) is calculated as the difference in the overall reward received, that is accuracy or loss, when he is included versus when he is not included in the coalition.

Mathematically, Shapley value to player iii can be expressed as

 ϕ i(v) = ∑ |S|! (|N|−|S|−1)! [v(S∪{i}) −v(S)]

S⊆N∖{i} ∣N∣!

Where:

- \bullet v(S) is the characteristic function representing the performance of subset S.
- N is the set of all players (neurons).
- ϕ i(v) is the Shapley value of player i, representing its fair contribution to the overall value.

Applying Shapley's Theory to Neural Networks

In neural networks, the neurons are "players," and the overall performance of a network (its accuracy or loss) is the total value of the game. The Shapley value of each neuron measures how much that neuron contributes to the network's performance.

Following this concept, Shapley pruning determines the neurons contributing towards the network's decision-making capabilities and those that may be nullified without a significant loss of performance. It proves very useful for the compression of models as it reduces the network in terms of size and complexity while preserving accuracy.

Complete explanation of "Shapley Pruning for Neural Network Compression" by 2024.

The focus has instead gone to compression using Shapley pruning for compressing neural networks to the mutual goals of reduction both in size and complexity of deep architectures in learning, all of these in recent years without loss of effectiveness.

This technique using the Shapley value relates to a principle of cooperative game theory that describes the importance of specific neurons or connections contained in a neural network. Shapley pruning identifies the less crucial elements of a network and eliminates them to allow for effective compression accompanied by model accuracy.

What constitutes Shapley Pruning?

Shapley pruning is a form of model compression applied to neural networks. Here, the contribution of each neuron or connection to the network's performance has been evaluated by using Shapley values.

With the results from computing a Shapley value for every neuron, we may determine which neurons should be removed (pruned) to compress the model, without losing much in predictive performance, both in terms of reduction in the model size and a decrease in associated computational complexity.

Shapley pruning measures the contribution of every neuron within a neural network to its output by applying Shapley values. Neurons with lower Shapley values-that is, neurons whose influence on the performance of the network is smaller-contribute less to its overall performance and are selected as being likely for pruning. Those whose "Shapley value" is higher contribute significantly to the performance of a model and are retained.

Basic Elements of Shapley Pruning:

1. Shapley Value (Game Theory): The Shapley value is a concept from cooperative game theory which seeks to fairly apportion the total value generated by a coalition of players-neurons, in this case-to each player based on their contribution to the success of the coalition (model performance).

The value assigned to every neuron is determined by studying all the possible subsets of neurons, and by estimating how much including that neuron would affect the end performance of the network.

2. Shapley Pruning Process: The Shapley pruning procedure can now be described by the following steps:

1. Conceptualize the neural network as a game with each neuron being a "player" and acting in a cooperative way. The overall objective of the game would be improving the performance - for example, accuracy-of the network.

2. Characteristic Function: The characteristic function will serve the purpose of assigning a performance measure, accuracy or loss, to each subset of neurons within the network. Removing certain specified neurons from the network results in a degradation of performance, and such degraded performance is attributed to those excluded neurons.

3.Marginal Contribution: Shapley value for a neuron will be calculated by computing its marginal contribution to all possible subsets of neurons. A neuron's marginal contribution is the difference in performance when the neuron is in a subset versus out of a subset.

4. Neuron Ranking: Once Shapley values are calculated, neurons are ranked according to their contributions. Low Shapley values indicate less important neurons and thus candidates for pruning.

5. Pruning Neurons: The neurons that have the smallest Shapley values are removed from the network. The surviving neurons, those neurons with high Shapley values, are responsible for maintaining high-performance in the model.

6. Fine-Tuning: It is possible to fine-tune the network after pruning to regain any potential loss in accuracy and optimize the remaining structure.

3. Benefits of Shapley Pruning:

Efficient Compression: The implementation of Shapley pruning facilitates a notable decrease in the quantity of neurons or weights within the neural network, while only marginally impacting its accuracy.

Performance: The network gets more efficient and faster by taking away redundant or less important neurons, thus reducing extra computational overhead during inference as well as training.

Interpretability: Shapley values offer a clear interpretation of which neurons are important for making a given decision of the model.

Better Generalization: Pruning fewer important neurons can potentially improve the generalization of the model by reducing overfitting to noise or irrelevant features.

4.Challenges and Limitations:

Computational Expense: The determination of precise Shapley values can incur significant computational demands, especially within extensive networks. The requirement to assess performance over numerous subsets of neurons contributes to the time-intensive nature of this procedure.

Approximation: The high computational cost often leads to the application of approximations. They deliver only slightly less accurate results compared with the Shapley values in approximating, but these are still highly effective for pruning.

Shapley Pruning Process - Steps and Suggested Figures

Step 1: Define the Network as a "Game"

- **Description:** In Shapley Pruning, each neuron in a layer is treated as a "player" in a game, where different combinations of neurons (called "coalitions") represent subsets that contribute differently to the model's performance. This game theory framework sets the stage for evaluating each neuron's impact based on its interactions with others.
- **Figure 1:** A simple neural network layer illustration where each neuron is labeled as a "player." Draw lines connecting groups of neurons to illustrate possible coalitions.

Step 2: Establish a Characteristic Function (Performance Metric)

- **Description:** Create a function that measures the performance (accuracy) of each coalition. This function assesses the impact of each subset of neurons on the model's accuracy. When certain neurons are pruned (left out), the performance metric (accuracy) often decreases, showing the contribution of each subset.
- **Figure 2:** A bar graph showing different coalitions (subsets of neurons) on the x-axis and their corresponding accuracies on the y-axis. Larger subsets result in higher accuracy, while smaller subsets show lower accuracy.

Step 3: Calculate the Shapley Value for Each Neuron

- **Description:** Using the characteristic function, compute the Shapley value for each neuron, which measures the average marginal contribution of that neuron across all possible coalitions. This helps determine each neuron's unique importance based on its added value to each subset.
- **Figure 3:** An illustration of Shapley value calculation for a specific neuron. Show multiple subsets of neurons and the impact of adding this neuron on accuracy for each subset. Summing up and averaging these marginal contributions would yield the Shapley value.

Step 4: Rank Neurons Based on Shapley Values

- **Description:** With each neuron's Shapley value calculated, neurons are ranked based on their contributions to performance. Neurons with the lowest Shapley values contribute the least to accuracy, making them the primary candidates for pruning.
- **Figure 4:** A bar plot where neurons are arranged by their Shapley values in descending order, highlighting lowvalue neurons as potential pruning targets.

Step 5: Prune Neurons with Low Shapley Values and Fine-tune the Model

- **Description:** Prune the neurons with the lowest Shapley values and fine-tune the model, if necessary, to recover any performance loss. This step is crucial to maintaining model performance after reducing complexity.
- **Figure 5:** Side-by-side comparison of the original network and the pruned network, where the pruned network has fewer neurons. An additional chart could show model accuracy before and after fine-tuning.

Step 6: Validate the Pruned Model

- **Description:** After pruning, evaluate the model on validation data to ensure accuracy is within acceptable limits. If accuracy loss is observed, further fine-tuning may be required.
- **Figure 6:** A line graph comparing the accuracy of the original and pruned models across validation data, showing performance stability or recovery.

Step 7: Implement Compression Techniques (Optional)

- **Description:** In some cases, additional compression techniques, such as quantization or weight sharing, can be applied to further reduce model size without sacrificing accuracy.
- **Figure 7:** An illustration showing compression techniques applied to the pruned network, with a smaller model size depicted post-compression.

Step 8: Deploy the Compressed Model

- **Description:** Once the pruned and compressed model is validated, it's ready for deployment on resourceconstrained devices, where it will operate more efficiently due to the reduced model size and complexity.
- **Figure 8:** Show a diagram of the deployment process, with the compressed model represented on a mobile or edge device for real-time applications.

This approach with descriptive steps and figures helps clarify each phase in the Shapley pruning method, from defining neuron contributions to model deployment. Let me know if you would like further details or additional figures created for any of these steps.

3. RELATED WORKS

Recently, attention had been focused on the application of DRL in algorithmic and quantitative trading as it can tackle tough problems in the financial markets. Currently, many research initiatives are being carried out, but they are unique in methodology or advancement in the implementation of DRL with better trading strategies, risk management, and portfolio optimization. It covers several domains of trading, namely, portfolio optimization, high-frequency trading, and

statistical arbitrage within the constraints of standard approaches to machine learning in dynamic, turbulent market conditions.

The next section briefly reports on key studies pushing the adoption of DRL in finance from the perspectives of research themes, methodologies, and key findings.

The two studies combine to demonstrate how Shapley values-the concept of cooperative game theory-can be applied to neural network pruning for model compression. It is an idea that proposes that the contribution of each neuron in the network towards its performance can be measured, and those having less contribution towards accuracy can be pruned so that the size, speed, and efficiency of the network are decreased while still maintaining the capacity to make accurate predictions. Shapley pruning reduces the complexity of neural networks in a fair and interpretable way with as little degradation in performance as possible. It has been successfully applied to many architectures, including deep networks, and is part of the growing field of model interpretability and efficiency in machine learning.

4. ADVANCEMENT IN NEURAL NETWORK

Neural networks have made dramatic progress over the last two years, leading to tremendous innovation in machine learning, artificial intelligence, and deep learning. Developments were made in the four following areas: models, optimization techniques, interpretability, and real-world applications. Some of the main highlights include the following:

1. Developed Neural Network Architectures

Deep Convolutional Neural Networks (CNNs): CNNs were originally invented for image recognition; enormous depth and efficiency improvements with architectures of ResNet, DenseNet, and EfficientNet have been seen.

ResNet: Introduces skip connections into networks that prevent vanishing gradients, allowing much deeper networks than those trained before.

EfficientNet does use compound scaling for optimization of depth, width, and resolution in the networks to achieve better efficiency with fewer parameters.

Transformer Networks: First proposed for NLP, transformers shake things up here because they allow models as BERT, GPT and T5 broadly bringing unprecedented results in language tasks.

Self-attention mechanisms enable transformers to focus relevant parts of input data to show better performance across different tasks, especially with tasks like machine translation, summarization, and question answering.

ViT: In an inspiration from the transformers in natural language processing, the transformers have been adapted to computer vision with much success in beating traditional CNNs at tasks in image classification.

Generative Models; GANs, VAEs: GAN and VAE are opening a new frontier of applications in generating images, data augmentation as well as unsupervised learning.

GANs; GANs generically consist of a generator network and a discriminator network, acting as adversaries; hence, GANs can generate high-quality data images which might be a deep fake in images or a realistic painting.

VAEs are primarily applied to probabilistic modeling and generative modeling of new data samples originating from the same distribution as the training data.

2. Self-Supervised Learning (SSL)

Self-supervised learning is a paradigm that enables models to learn directly from unlabeled data, through generating pretext tasks that do not necessarily require labeled datasets for them. This has brought about a sea change in areas where labeled data is scanty or unreasonably expensive to procure.

The most common self-supervised methods are SimCLR and BYOL. These techniques enable networks to learn representations from unlabeled data.

Self-supervised learning has been widely applied in NLP(BERT) and computer vision like SimCLR, reaching state-ofthe-art results but using much less labeled data.

3. Reinforcement Learning (RL) and Neural Networks

The growth of RL has been remarkable, especially in conjunction with deep learning techniques-an area known as Deep Reinforcement Learning, or DRL.

AlphaGo from DeepMind demonstrated the power of DRL in defeating the world champion at the game of Go. This led to further development with AlphaZero that extended the technique even more to chess and other board games.

The field of RL has also been applied to robotics, autonomous driving, and real-time decision-making systems.

Actor-Critic Methods: Hybridization between value-based and policy-based approaches used in actor-critic methods has greatly improved the stability and efficiency of training neural networks with reinforcement tasks.

4. Neural Architecture Search (NAS)

Neural Architecture Search NAS is the automation of the design of neural network architectures by NAS. The design of optimal architectures for specific tasks can be found by NAS without human intervention. Techniques like Reinforcement Learning and evolutionary algorithms explore the design space of neural architectures.

NAS has led to better-performing models such as EfficientNet and MNASNet that are mobile-device-aware and specifically optimized for edge applications.

5. Neural Network Compression and Efficiency

Because of the vastly growing size of neural networks, there is an interconnected interest in their compression and efficiency for deployment on edge devices. Some of the techniques are:

Pruning: Weight or neuron removals that are unimportant- as with Shapley pruning.

Quantization: Weights accuracy is reduced in order to save memory and speed up inference.

Knowledge Distillation: Large model, teacher, compressed to a smaller student that could attain similar performance.

Low-Rank Factorization: Matrix factorization into low-rank approximations to reduce model size and cost of computation.

6. Transfer Learning and Fine-Tuning

Transfer learning lets previously trained models be reused for other related tasks, and with a drastic reduction in training time and data requirements.

The BERT and GPT models have been fine-tuned for a wide range of NLP tasks, like sentiment analysis and machine translation, thus enabling faster deployment into real-world applications.

In computer vision, other tasks like object detection, segmentation, and style transfer are performed using fine-tuned ImageNet pre-trained CNNs.

7. Explainable AI (XAI) and Model Interpretability

Interpretability and explainability have emerged as two important areas because deep learning models are being used to increasingly high-stakes applications like in healthcare, finance, etc.

SHapley Additive exPlanations SHAP and LIME (Local Interpretable Model-agnostic Explanations) are among the recent tools for understanding how deep learning models make decisions by offering feature importance scores.

These advances help to make neural networks more transparent and trustworthy from the point of the users, especially in fields that require regulatory compliance.

8. Federated Learning

Federated Learning is a type of distributed ML wherein models are trained across multiple decentralized devices, such as mobile phones, all without having to share data.

It's an application of the technique of privacy-preserving learning that allows model building while keeping data local.

This approach is gaining much recognition in applications like predictive text, medical data analysis, and optimization for mobile apps - where data privacy is a crucial concern.

9. AI Hardware Acceleration

Advances in hardware, including GPUs, TPSs, and neuromorphic chips, are allowing for rapid training and deployment of neural networks.

These accelerators are designed to easily support the high-computational requirements of deep learning models.

Quantum computing is yet another area of research for AI. It promises to revolutionize neural network training due to much faster computation on specific tasks.

10. Multimodal Neural Networks

Multimodal learning refers to combining the information from various sources, such as text, images, and audio to develop more robust and versatile models. Examples of such models include CLIP (Contrastive Language-Image Pre-Training), which combines both text and images for zero-shot classification and generation of images from their descriptions.

5. BACKGROUND PROBLEM

The problems in the background of the field of neural networks, its application in machine learning (ML) and deep learning (DL), are highly important, especially with complexities, scalability, and practical challenges deployed in those models. Some of the core problems and challenges faced within this field are as follows:

1.Computational Complexity: Training large models is resource-intensive, requiring significant amounts of computing power, specialized hardware, and energy; it turns out to be expensive and inefficient.

2.Overfitting and Generalization: Neural networks often tend to overfit training data rather than generalizing well for unseen data, especially deep architectures.

3.Data Scarcity: Neural networks consume large labeled datasets that are expensive to collect. Unlabeled data is challenging for many tasks.

4.Model Interpretability: Neural networks are "black boxes," and it becomes problematic to understand how they decide to make the decisions, which is critical for many applications.

5.Challenges in Deployment: Deep models require large amounts of memory and compute resources, and real-time inference is generally not possible in most edge devices.

6.Bias and Fairness: The models are often imbued with the characteristics of the training data, which may indicate unfairness in selections in particularly sensitive fields, like hiring and criminal justice.

7.Training Instability: Training may get unstable due to issues of vanishing or exploding gradients, especially when using deep or recurrent networks.

8.Transfer Learning Problems: It might be difficult to apply the pre-trained model to a new task or domain; it often is challenging regarding the availability of data and generalizability among tasks.

9.Adversarial Attacks: A small perturbation in the input that triggers the misclassification can be caused in neural networks, making some cases raise security concerns.

10.Ethical and Social Impact: There are ethical concerns in terms of privacy, transparency in decision-making, and the possible loss of jobs due to automation by AI.

11.Scalability: Scaling models to new tasks or domains is particularly challenging, and so is generalizing the model with limited data.

6. METHODOLOGIES

The methodologies adopted in the design, training, and optimization of models in neural networks are aimed at achieving better accuracy, efficiency, and generalization. They cut across different stages, all the way from model architecture design to training strategy. Here are some key methodologies utilized in the neural networks:

1. Supervised Learning

This is the most commonly used type of training, where the model learns from labelled data. The goal is to learn a mapping from input features to output labels.

• Loss Function: This is the model trained to minimize a loss function. There are common ones, such as mean squared error for regression or cross-entropy loss for classification.

• **Optimization Algorithm:** We usually use a variant of stochastic gradient descent, such as SGD or Adam or RMSprop to decrease the loss function.

Key Formula:

$$
L(\theta) = \frac{1}{N} \sum_{i=1}^{N} \text{Loss}(f(x_i, \theta), y_i)
$$

where $L(\theta)$ is the loss function, xi is the input, yi is the target output, and $f(xi, \theta)$ is the predicted output of the neural network with parameters θ.

2. Unsupervised Learning

In unsupervised learning, the output in training neural networks on data lacking output; the objective remains to be the finding of patterns, structures, or representations that stand within the data. Autoencoders: Networks trained to map input data onto a compressed latent representation followed by reconstruction of the input.

Generative Adversarial Networks: Are two networks - generative and discriminative - which play against each other and, in doing so, generate realistic data.

Example Formula (Autoencoder):

$$
L = |x - \hat{x}|_2^2
$$

Here:

- L is the loss.
- \bullet x is the input,
- x is the reconstructed input (represented with a hat symbol),
- $|\cdot|^2$ represents the squared L $_2$ norm.

3. Reinforcement Learning

Reinforcement learning entails a neural network that learns to determine the best action with which it should make a decision given its interaction in the environment it operates within. Interactions and decisions, based on the reaction of the application, are reviewed in terms of either rewards or penalties.

Q-Learning: The value function $Q(s,a)$ defined as the expected future reward given the state s and action a; knowledge update of the model is done directly on observed rewards.

$$
Q(s_t, a_t) \leftarrow Q(s_t, a_t) + \alpha \left(r_{t+1} + \gamma \max_{a'} Q(s_{t+1}, a') - Q(s_t, a_t)\right) \text{ (equation)}
$$

- $Q(s_t, a_t)$ is the Q value for state s_t and action a_t .
- (r_{t+1}) : Reward received att ime(t + 1).
- γ is the Discount factor.
- α is the Learning rate.

4. Convolutional Neural Networks (CNNs)

CNNs are specially designed to allow the convolution layers to be exploited as they accept grid-like data. Patterns such as edges, textures, and objects can easily be detected using this kind of network.

Convolution Operation: Essentially, it consists of sliding the operation of a filter that's also known as the kernel over the input to produce a feature map.

Convolution Formula:

$$
y(i,j) = \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} x(i+m, j+n) w(m,n)
$$

where:

- $x(i, j)$ is the input image,
- \bullet w(m, n) is the convolution kernel,
- $y(i, j)$ is the output feature map.

5. Recurrent Neural Networks (RNNs):

RNNs are designed for sequential data where the output depends not just on the current input but also on the previous ones.

Vanilla RNN: The output at one timestep is treated as an input to the next one.

RNN Formula:

$$
h_t = \sigma(Wx_t + Uh_{t-1} + b)
$$

Here:

- h_t is the hidden state at time t,
- x_t is the input at time t,
- W is the weight matrix for the input,
- U is the weight matrix for the previous hidden state h_{t-1}
- b is the bias term,
- $σ$ is the activation function (e.g., sigmoid, tanh).

6. Long Short-Term Memory (LSTM) and Gated Recurrent Units (GRUs)

These are advanced RNNs that have addressed the vanishing gradient problem in long sequences. They use gating mechanisms to control information flow.

LSTM: It consists of memory cells and gates, which control the flow of information. LSTM Formula:

$$
f_{t} = \sigma(W_{f}x_{t} + U_{f}h_{t-1} + b_{f})
$$

\n
$$
i_{t} = \sigma(W_{i}x_{t} + U_{i}h_{t-1} + b_{i})
$$

\n
$$
o_{t} = \sigma(W_{o}x_{t} + U_{o}h_{t-1} + b_{o})
$$

\n
$$
c_{t} = f_{t} \cdot c_{t-1} + i_{t} \cdot \tanh(W_{c}x_{t} + U_{c}h_{t-1} + b_{c})
$$

\n
$$
ht = ot * \tanh(ct)
$$

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7. EXPLANATION OF TERMS

- **:** FORGET GATE
- **i_t:** INPUT GATE
- **o**_t: Output gate
- \bullet \mathbf{c}_t : Cell state
- ht: HIDDEN STATE
- \bullet \mathbf{x}_t : INPUT AT TIME STEP TTT
- h_{t-1} : HIDDEN STATE FROM THE PREVIOUS TIME STEP
- W, U, b: WEIGHTS AND BIASES
- σ : SIGMOID ACTIVATION FUNCTION
- tanh: HYPERBOLIC TANGENT ACTIVATION FUNCTION

8. CONCLUSION

His research into neural network compression and pruning reveals an amazing bulk of works on reducing the complexity of neural networks, keeping good performance within quite reasonable bounds. Thus, methods like that optimize neural networks through the elimination of redundant neurons, weights, or layers with the purposes of faster computations, lower memory consumption, and more efficient models.

New techniques of pruning, such as Shapley pruning, rate the importance assigned to each neuron based on the contribution it lends to the main outcome using cooperative game theory. It will avoid redundancy by retaining its most valued parts. Shapley Pruning is a very interesting method since it attempts to provide some Shapley value for each neuron based on the cooperative game-theory paradigm. This will make pruning more systematic and mathematically grounded by permitting the pruning of more neurons without significantly affecting performance. Advanced pruning techniques enabled the integration of reinforcement learning (Q-learning) with LSTMs and other deep learning models, including dynamic feedback mechanisms and sequential decision-making processes that optimize performance over several applications. Mathematical formulations like autoencoder, Q-learning, and LSTM gates make us understand how the models learn and update their parameters. In this respect, these methods are all related to backpropagation in that it propagates errors backward through the network with an objective of adjusting the weights for minimizing loss.

The experiments show that pruning, although it reduces the size and complexity of models significantly, has such sizes and complexities that sensitive setting tuning of its operating parameters is necessary not to lose the accuracy of the model. Techniques like fine-tuning after pruning and Shapley value-based pruning reduce these losses in accuracy.

Conclusion: Shapley pruning and neural network compression are promising avenues for efficiency and practical applicability in deep learning models, in spite of their resource-intensive nature. These techniques can be developed further along with new mathematical tools created and the areas of application of these techniques will form the framework for the future of machine learning and artificial intelligence.

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